# String Constraints for Verification 

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#### Abstract

We present a decision procedure for a logic that combines (i) word equations over string variables denoting words of arbitrary lengths, together with (ii) constraints on the length of words, and on (iii) the regular languages to which words belong. Decidability of this general logic is still open. Our procedure is sound for the general logic, and a decision procedure for a particularly rich fragment that restricts the form in which word equations are written. In contrast to many existing procedures, our method does not make assumptions about the maximum length of words. We have developed a prototypical implementation of our decision procedure, and integrated it into a CEGAR-based model checker for the analysis of programs encoded as Horn clauses. Our tool is able to automatically establish the correctness of several programs that are beyond the reach of existing methods.


## 1 Introduction

Software model checking is an active research area that has witnessed a remarkable success in the past decades $[15,8]$. Mature model checking tools are already used in industrial applications [2]. One main reason for this success are recent developments in SMT technology [5, 7, 3], which enable efficient reasoning about symbolic representations of different data types in programs. This dependence encompasses, however, that model checking tools are inherently limited by the data types that can be handled by the underlying SMT solver. A data type for which satisfying decision procedures have been missing is that of strings. Our work proposes a rich string logic together with a decision procedure targeting model checking applications.

String data types are present in all conventional programming and scripting languages. In fact, it is impossible to capture the essence of many programs, for instance in database and web applications, without the ability to precisely represent and reason about string data types. The control flow of programs can depend on the words denoted by the string variables, on the length of words, or on the regular languages to which they belong. For example, a program allowing users to choose a username and a password may require the password to be of a minimal length, to be different from the username, and to be free from invalid
characters. Reasoning about such constraints is also crucial when verifying that database and web applications are free from SQL injections and other security vulnerabilities.

Existing solvers for programs manipulating string variables and their length are either unsound, not expressive enough, or lack the ability to provide counterexamples. Many solvers $[9,23,24]$ are unsound since they assume an a priori fixed upper bound on the length of the possible words. Others $[9,17,26]$ are not expressive enough as they do not handle word equations, length constraints, or membership predicates. Such solvers are mostly aimed at performing symbolic executions, i.e., establishing feasibility of paths in a program. The solver in [25] performs sound over-approximation, but without supplying counterexamples in case the verification fails. In contrast, our decision procedure specifically targets model checking applications. In fact, we use it in a prototype model checker in order to automatically establish program correctness for several examples.

Our decision procedure establishes satisfiability of formulae written as Boolean combinations of: (i) word (dis)equations such as ( $a \cdot u=v \cdot b$ ) or $(a \cdot u \neq v \cdot b)$, where $a, b$ are letters and $u, v$ are string variables denoting words of arbitrary lengths, (ii) length constraints such as $(|u|=|v|+1)$, where $|u|$ refers to the length of the word denoted by string variable $u$, and (iii) predicates representing membership in regular expressions, e.g., $u \in c \cdot(a+b)^{*}$. Each of these predicates can be crucial for capturing the behavior and establishing the correctness of a string-manipulating program (cf. the program in Section 2). The analysis is not trivial as it needs to capture subtle interactions between different types of predicates. For instance, the formulae $\phi_{1}=(a \cdot u=v \cdot b) \wedge(|u|=|v|+1)$ and $\phi_{2}=(a \cdot u=v \cdot b) \wedge v \in c \cdot(a+b)^{*}$ are unsatisfiable, i.e., there is no possible assignment of words to $u$ and $v$ that makes the conjunctions evaluate to true. To capture this, the analysis needs to propagate facts from one type of predicates to another; e.g., in $\phi_{1}$ the analysis deduces from $(a \cdot u=v \cdot b)$ that $|u|=|v|$, which results in an unsatisfiable formula $(|u|=|v| \wedge|u|=|v|+1))$. The general decidability problem is still open. We guarantee termination of our procedure for a fragment of the full logic that includes the three types of predicates. The fragment we consider is rich enough to capture all the practical examples we have encountered.

We have integrated our decision procedure in a prototype model checker and used it to verify properties of implementations of common string manipulating functions such as the Hamming and Levenshtein distances. Predicates required for verification can be provided by hand; to achieve automation, in addition we propose a constraint-based interpolation procedure for regular word constraints. In combination with our decision procedure for words, this enables us to automatically analyze programs that are currently beyond the reach of state-of-the-art software model checkers.

Related Work. The pioneering work by Makanin [18] proposed a decision procedure for word equations (i.e., Boolean combinations of (dis)equalities) where the variables can denote words of arbitrary lengths. The decidability problem is already open [4] when word equations are combined with length constraints of
the form $|u|=|v|$. Our logic adds predicates representing membership in regular languages to word equations and length constraints. This means that decidability is still an open problem. A contribution of our work is the definition of a rich sub-logic for which we guarantee the termination of our procedure.

In a work close to ours, the authors in [10] show decidability of a logic that is strictly weaker than the one for which we guarantee termination. For instance, in [10], membership predicates are allowed only under the assumption that no string variables can appear in the right hand sides of the equality predicates. This severely restricts the expressiveness of the logic. In [26], the authors augment the Z3 [7] SMT solver in order to handle word equations with length constraints. However, they do not support regular membership predicates. In our experience, these are crucial during model checking based verification.

Finally, in addition to considering more general equations, our work comes with an interpolation-based verification technique adapted for string programs. Notice that neither of $[10,26]$ can establish correctness of programs with loops.

Outline. In the next section, we use a simple program to illustrate our approach. In Section 3 we introduce a logic for word equations with arithmetic and regular constraints, and then describe in Section 4 a procedure for deciding satisfiability of formulae in the logic. In Section 5 we define a class formulae for which we guarantee the termination of our decision procedure. We describe the verification procedure in Section 6 and the implementation effort in Section 7. Finally in Section 8 we give some conclusions and directions for future work.

## 2 A Simple Example

In this section, we use the simple program listed in Fig. 1 to give a flavor of our verification approach. The listing makes use of features that are common in string manipulating programs. We will argue that establishing correctness for such programs requires: (i) the ability to refer to string variables of arbitrary lengths, (ii) the ability to express combinations of constraints, like that the words denoted by the variables belong to regular expressions, that their lengths obey arithmetic inequalities, or that the words themselves are solutions to word equations, and (iii) the ability for a decision procedure to precisely capture the subtle interaction between the different kinds of involved constraints.

In the program of Fig. 1, a string variable s is initialized with the empty word. A loop is then executed an arbitrary number of times. At each iteration of the loop, the instruction $s=$ ' $a$ ' $+s+$ ' $b$ ' appends the letter ' $a$ ' at the beginning of variable s and the letter ' $b$ ' at its end. After the loop, the program asserts that s does not have the word 'ba' as a substring (denoted by !s.contains ('ba'), and that its length (denoted by s.length()) is even.

Observe that the string variable $s$ does not assume a maximal length. Any verification procedure that requires an a priori fixed bound on the length of the string variables is necessarily unsound and will fail to establish correctness.

Moreover, establishing correctness requires the ability to express and to reason about predicates such as those mentioned in the comments of the code in

```
// Pre= (true)
String s= '';
// P}\mp@subsup{P}{1}{}=(s\in\epsilon
while(*){
    // P}\mp@subsup{P}{2}{}=(s=u\cdotv\wedgeu\in\mp@subsup{a}{}{*}\wedgev\in\mp@subsup{b}{}{*}\wedge|u|=|v|
    s='a' + s + 'b';
}
// P}\mp@subsup{P}{3}{}=\mp@subsup{P}{2}{
assert(!s.contains('ba') && (s.length() % 2) == 0);
// Post = P P
```

Fig. 1. A simple program manipulating a string variable $s$. Our logic allows to precisely capture the word equations, membership predicates and length constraints that are required for validating the assertion is never violated. Our decision procedure can then automatically validate the required verification conditions described in Fig. 2.

```
\(v c_{1}: \operatorname{post}(\) Pre, \(\mathbf{s}=" ") \Longrightarrow P_{1}\)
\(v c_{2}: P_{1} \Longrightarrow P_{2}\)
\(v c_{3}: \operatorname{post}\left(P_{2}, \mathrm{~s}=" \mathrm{a} " \cdot \mathrm{~s} \cdot " \mathrm{~b} "\right) \Longrightarrow P_{2}\)
\(v c_{4}: P_{2} \Longrightarrow P_{3}\)
\(v c_{5}: \operatorname{post}\left(P_{3}\right.\), assume (s.contains("ba") || !(s.length() \(\left.\left.\left.\% 2==0\right)\right)\right) \Longrightarrow\) false
\(v c_{6}: \operatorname{post}\left(P_{3}\right.\), assume(!s.contains("ba") \&\& (s.length() \(\left.\left.\left.\% 2==0\right)\right)\right) \Longrightarrow\) Post
```

Fig. 2. Verification conditions for the simple program of Fig. 1.

Fig. 1. For instance, the loop invariant $P_{2}$ states that: (i) the variable $s$ denotes a finite word $w_{s}$ of arbitrary length, (ii) that $w_{s}$ equals the concatenation of two words $w_{u}$ and $w_{v}$, (iii) that $w_{u} \in a^{*}$ and $w_{v} \in b^{*}$, and (iv) that the length $\left|w_{u}\right|$ of word $w_{u}$ equals the length $\left|w_{v}\right|$ of word $w_{v}$.

Using the predicates in Fig. 1, we can formulate program correctness in terms of the validity of each of the implications listed in Fig. 2. For instance, validity of the verification condition $v c_{5}$ amounts to showing that $\neg v c_{5}=(s=u \cdot v \wedge u \in$ $\left.a^{*} \wedge v \in b^{*} \wedge|u|=|v|\right) \wedge\left(s=s_{1} \cdot b \cdot a \cdot s_{2} \vee \neg(|s|=2 n)\right)$ is unsatisfiable. To establish this result, our decision procedure generates the two proof obligations $\neg v c_{51}:\left(s=u \cdot v \wedge u \in a^{*} \wedge v \in b^{*} \wedge|u|=|v| \wedge s=s_{1} \cdot b \cdot a \cdot s_{2}\right)$ and $\neg v c_{52}:\left(s=u \cdot v \wedge u \in a^{*} \wedge v \in b^{*} \wedge|u|=|v| \wedge \neg(|s|=2 n)\right)$.

In order to check $v c_{51}$, the procedure symbolically matches all the possible ways in which a word denoted by $u \cdot v$ can also be denoted by $s_{1} \cdot b \cdot a \cdot s_{2}$. For instance, $u=s_{1} \cdot b \wedge v=a \cdot s_{2}$ is one possible matching. In order to be able to show unsatisfiability, the decision procedure has to also consider the other possible matchings. For instance, the case where the word denoted by $u$ is a strict prefix of the one denoted by $s_{1}$ has also to be considered. For this reason, the matching process might trigger new matchings. In general, there is no guarantee that the sequence of generated matchings will terminate. However, we show that this sequence terminates for an expressive fragment of the logic. This fragment includes the predicates of mentioned in this section and all predicates
we encountered in practical programs, The procedure then checks satisfiability of each such a matching. For instance, the matching $u=s_{1} \cdot b \wedge v=a \cdot s_{2}$ is shown to be unsatisfiable due the the membership predicate $v \in b^{*}$. In fact our procedure automatically proves that $\neg v_{51}$ is not satisfiable after checking all possible matchings.

So for $\neg v c_{5}$ to be satisfiable, $\neg v c_{52}$ needs to be satisfiable. Our procedure deduces that this would imply that $|u|=|v| \wedge \neg(|u|+|v|=2 n)$ is satisfiable. We leverage on existing standard decision procedures for linear arithmetic in order to show that this is not the case. Hence $\neg v c_{5}$ is unsatisfiable and $v c_{5}$ is valid. For this example, and those we report on in Section 6, our procedure can establish correctness fully automatically given the required predicates.

Observe that establishing validity requires the ability to capture interactions among the different types of predicates. For instance, establishing validity of $v c_{5}$ involves the ability to combine the word equations ( $s=u \cdot v \wedge s=s_{1} \cdot b \cdot a \cdot s_{2}$ ) with the membership predicates $\left(u \in a^{*} \wedge v \in b^{*}\right)$ for $v c_{51}$, and with the length constraints $(|u|=|v| \wedge \neg(|s|=2 n))$ for $v c_{52}$. Capturing such interactions is crucial for establishing correctness and for eliminating false positives.

## 3 Defining the String Logic $\mathcal{E}_{e, r, l}$

In this section we introduce a logic, which we call $\mathcal{E}_{e, r, l}$, for word equations, regular constraints (short for membership constraints in regular languages) and length and arithmetic inequalities. We assume a finite alphabet $\Sigma$ and write $\Sigma^{*}$ to mean the set of finite words over $\Sigma$. We work with a set $U$ of string variables denoting words in $\Sigma^{*}$ and write $\mathcal{Z}$ for the set of integer numbers.

Syntax. We let variables $u, v$ range over the set $U$. We write $|u|$ to mean the length of the word denoted by variable $u, k$ to mean an integer in $\mathcal{Z}, c$ to mean a letter in $\Sigma$ and $w$ to mean a word in $\Sigma^{*}$. The syntax of formulae in $\mathcal{E}_{e, r, l}$ is defined as follows:

$$
\begin{aligned}
& \phi::=\phi \wedge \phi|\neg \phi| \varphi_{e}\left|\varphi_{l}\right| \varphi_{r} \\
& \varphi_{e}::=\operatorname{tr}=\operatorname{tr} \mid \operatorname{tr} \neq \operatorname{tr} \quad \text { (dis)equalities } \\
& \varphi_{l}::=e \leq e \quad \text { arithmetic inequalities } \\
& \varphi_{r}::=t r \in \mathcal{R} \quad \text { membership predicates } \\
& \operatorname{tr}::=\epsilon|c| u \mid t r \cdot t r \quad \text { terms } \\
& \mathcal{R}::=\emptyset|\epsilon| c|w| \mathcal{R} \cdot \mathcal{R}|\mathcal{R}+\mathcal{R}| \mathcal{R} \cap \mathcal{R}\left|\mathcal{R}^{C}\right| \mathcal{R}^{*} \text { regular expressions } \\
& e::=k| | t r| | k * e \mid e+e \quad \quad \text { integer expressions }
\end{aligned}
$$

Assume variables $\left\{u_{i}\right\}_{i=1}^{n}$, terms $\left\{\operatorname{tr}_{i}\right\}_{i=1}^{n}$ and integer expressions $\left\{e_{i}\right\}_{i=1}^{n}$. We write $\phi\left[u_{1} / t r_{1}\right] \ldots\left[u_{n} / t r_{n}\right]$ (resp. $\phi\left[\left|u_{1}\right| / e_{1}\right] \ldots\left[\left|u_{n}\right| / e_{n}\right]$ ) to mean the formula obtained by syntactically substituting in $\phi$ each occurrence of $u_{i}$ by term $t r_{i}$ (resp. each occurrence of $\left|u_{i}\right|$ by expression $e_{i}$ ). Such a substitution is said to be well-defined if no variable $u_{i}$ (resp. $\left|u_{i}\right|$ ) appears in any $t r_{i}$ (resp. $e_{i}$ ).

The set of word variables appearing in a term is defined as follows: $\operatorname{Vars}(\epsilon)=$ $\emptyset, \operatorname{Vars}(c)=\emptyset, \operatorname{Vars}(u)=\{u\}$ and $\operatorname{Vars}\left(t r_{1} \cdot t r_{2}\right)=\operatorname{Vars}\left(\operatorname{tr}_{1}\right) \cup \operatorname{Vars}\left(\operatorname{tr}_{2}\right)$.

Semantics. The semantics of $\mathcal{E}_{e, r, l}$ is mostly standard. We describe it using a mapping $\eta$ (called interpretation) that assigns words in $\Sigma^{*}$ to string variables in $U$. We extend $\eta$ to terms as follows: $\eta(\epsilon)=\epsilon, \eta(c)=c$ and $\eta\left(t r_{1} \cdot t r_{2}\right)=$ $\eta\left(t r_{1}\right) \cdot \eta\left(t r_{2}\right)$. Every regular expression $\mathcal{R}$ is evaluated to the language $\mathcal{L}(\mathcal{R})$ it represents. Given an interpretation $\eta$, we define another mapping $\beta_{\eta}$ that associates a number in $\mathcal{Z}$ to integer expressions as follows: $\beta_{\eta}(k)=k, \beta_{\eta}(|u|)=$ $|\eta(u)|, \beta_{\eta}(|t r|)=|\eta(t r)|, \beta_{\eta}(k * e)=k * \beta_{\eta}(e)$, and $\beta_{\eta}\left(e_{1}+e_{2}\right)=\beta_{\eta}\left(e_{1}\right)+\beta\left(e_{2}\right)$. A formula in $\mathcal{E}_{e, r, l}$ is then evaluated to a value in $\{f f, t t\}$ as follows:

$$
\begin{array}{rlll}
\operatorname{val}_{\eta}\left(\phi_{1} \wedge \phi_{2}\right) & =t t & \text { iff } & \operatorname{val}_{\eta}\left(\phi_{1}\right)=t t \text { and } \operatorname{val}_{\eta}\left(\phi_{2}\right)=t t \\
v a l_{\eta}\left(\neg \phi_{1}\right) & =t t & \text { iff } & \operatorname{val}_{\eta}\left(\phi_{1}\right)=f f \\
\operatorname{val}_{\eta}(t r \in \mathcal{R}) & =t t & \text { iff } & \eta(t r) \in \mathcal{L}(\mathcal{R}) \\
\operatorname{val}_{\eta}\left(t r_{1}=t r_{2}\right) & =t t & \text { iff } & \eta\left(t r_{1}\right)=\eta\left(t r_{2}\right) \\
\operatorname{val}_{\eta}\left(t r_{1} \neq t r_{2}\right) & =t t & \text { iff } & \neg\left(\eta\left(t r_{1}\right)=\eta\left(t r_{2}\right)\right) \\
\operatorname{val}_{\eta}\left(e_{1} \leq e_{2}\right) & =t t & \text { iff } & \beta_{\eta}\left(e_{1}\right) \leq \beta_{\eta}\left(e_{2}\right)
\end{array}
$$

A formula $\phi$ is said to be satisfiable if there is an interpretation $\eta$ such that $v a l_{\eta}(\phi)=t t$. It is said to be unsatisfiable otherwise.

## 4 Inference Rules

In this section, we describe our set of inference rules for checking the satisfiability of formulae in the $\operatorname{logic} \mathcal{E}_{e, r, l}$ of Section 3. Given a formula $\phi$, we build a proof tree rooted at $\phi$ by repeatedly applying the inference rules introduced in this Section. We can assume, without loss of generality, that the formula is given in Disjunctive Normal Form. An inference rule is of the form:

$$
\text { NAME }: \frac{B_{1} B_{2} \ldots B_{n}}{A} \text { cond }
$$

In this inference rule, NAME is the name of the rule, cond is a side condition on $A$ for the application of the rule, $B_{1} B_{2} \ldots B_{n}$ are called premises, and $A$ is called the conclusion of the rule. (We omit the side condition cond from Name when it is $t t$.) The premises and conclusion are formulae in $\mathcal{E}_{e, r, l}$. Each application consumes a conclusion and produces the set of premises. The inference rule is said to be sound if the satisfiability of the conclusion implies the satisfiability of one of the premises. It is said to be locally complete if the satisfiability of one of the premises implies the satisfiability of the conclusion. If all inference rules are locally complete, and if $\phi$ or one of the produced premises turns out to be satisfiable, then $\phi$ is also satisfiable. If all the inference rules are sound and none of the produced premises is satisfiable, then $\phi$ is also unsatisfiable.

We organize the inference rules in four groups. We use the rules of the first group to eliminate disequalities. The rules of the second group are used to simplify equalities. The rules of the third group are used to eliminate membership predicates. The rules of the last group are used to propagate length constraints. In addition, we assume standard decision procedures [3] for integer arithmetic.

Lemma 1. The inference rules of this section are sound and locally complete.

### 4.1 Removing Disequalities

We use rules Not-EQ and Diseq-Split in order to eliminate disequalities. In rule Not-EQ, we establish that $\operatorname{tr} \neq \operatorname{tr} \wedge \phi$ is not satisfiable and close this branch of the proof. In the second rule Diseq-Split, we eliminate disequalities involving arbitrary terms. For this, we make use of the fact that the alphabet $\Sigma$ is finite and replace any disequality with a finite set of equalities. More precisely, assume a formula $\operatorname{tr} \neq t r^{\prime} \wedge \phi$ in $\mathcal{E}_{e, r, l}$. We observe that the disequality $\operatorname{tr} \neq t r^{\prime}$ holds iff the words $w_{t r}$ and $w_{t r^{\prime}}$ denoted by the terms $t r$ and $t r^{\prime}$ are different. This corresponds to one of three cases. Assume three fresh variables $u, v$ and $v^{\prime}$. In the first case, the words $w_{t r}$ and $w_{t r^{\prime}}$ contain different letters $c \neq c^{\prime}$ after a common prefix $w_{u}$. They are written as the concatenations $w_{u} \cdot c \cdot w_{v}$ and $w_{u} \cdot c^{\prime} \cdot w_{v^{\prime}}$ respectively. We capture this case using the set $\operatorname{SPLIT}_{\text {DISEQ-Split }}=\left\{t r=u \cdot c \cdot v \wedge t r^{\prime}=u \cdot c^{\prime} \cdot v^{\prime} \wedge \phi \mid c, c^{\prime} \in \Sigma\right.$ and $\left.c \neq c^{\prime}\right\}$. In the second case, the word $w_{t r^{\prime}}=w_{u}$ is a strict prefix of $w_{t r}=w_{u} \cdot c \cdot w_{v}$. We capture this with $\operatorname{SpLIT}_{\text {DISEQ-Split }}^{\prime}=\left\{t r=u \cdot c \cdot v \wedge t r^{\prime}=u \wedge \phi \mid c \in \Sigma\right\}$. In the third case, the word $w_{t r}=w_{u}$ is a strict prefix of $w_{t r^{\prime}}=w_{u} \cdot c^{\prime} \cdot w_{v}^{\prime}$, and we capture this case using the set $\operatorname{Split}_{\text {DISEQ-Split }}^{\prime \prime}=\left\{t r=u \wedge t r^{\prime}=u \cdot c \cdot v^{\prime} \wedge \phi \mid c \in \Sigma\right\}$.

$$
\begin{gathered}
\text { NoT-EQ }: \frac{*}{t r \neq t r \wedge \phi} \quad \mathrm{EQ}: \frac{\phi}{t r=t r \wedge \phi} \\
\text { DISEQ-SpLIT }: \frac{\operatorname{SPLIT}_{\text {DISEQ-Split }} \cup \operatorname{SPLIT}_{\text {DISEQ-SpLIT }}^{\prime} \cup \operatorname{SPLIT}_{\text {DISEQ-Split }}^{\prime \prime}}{t r \neq t r^{\prime} \wedge \phi}
\end{gathered}
$$

### 4.2 Simplifying Equalities

We introduce rules Eq, Eq-VAR, and Eq-Word to manipulate equalities. Rule applications take into account symmetry of the equality operator (i.e., if a rule can apply to $w \cdot t r_{1}=t r_{2} \wedge \phi$ then it can also apply to $\left.t r_{2}=w \cdot t r_{1} \wedge \phi\right)$. Rule EQ eliminates trivial equalities of the form $t r=t r$.

Rule Eq-Var eliminates variable $u$ from the equality $u \cdot t r_{1}=t r_{2} \wedge \phi$. Let $w_{u}$ be some word denoted by $u$. For the equality to hold, $w_{u}$ must be a prefix of the word denoted by $t r_{2}$. There are two cases. The first case, represented by Split $_{\text {Eq-VAR }}$ in EQ-VAR, captures situations where $w_{u}$ coincides with a word denoted by a prefix $t r_{3}$ of $t r_{2}$. The second case, represented by Split ${ }_{\text {Eq-Var }}^{\prime}$, captures situations where $w_{u}$ does not coincide with a word denoted by a prefix of $t r_{2}$. Instead, $t r_{2}$ can be written as $t r_{3} \cdot v \cdot t r_{4}$ and the word $w_{u}$ is written as the concatenation of two words, one that is denoted by $t r_{3}$ and another that is prefix of the word denoted by $v$.

$$
\text { EQ-VAR }: \frac{\operatorname{SPLIT}_{\mathrm{EQ}-\mathrm{VAR}} \cup \operatorname{SPLIT}_{\mathrm{EQ}-\mathrm{VAR}}^{\prime}}{u \cdot t r_{1}=t r_{2} \wedge \phi}
$$

The set Spliteq-Var $_{\text {Eap }}$ captures the first case, when $w_{u}$ coincides with a word denoted by a prefix $t r_{3}$ of $t r_{2}$. The premises for this case are partitioned into two sets, namely $\operatorname{Split}_{\mathrm{Eq}-\mathrm{VAR}-1}$ and $\mathrm{Split}_{\mathrm{Eq}-\mathrm{Var}-2}$ :

$$
\begin{aligned}
\operatorname{SPLIT}_{\mathrm{EQ}-\mathrm{VAR}-1} & =\left\{\begin{array}{l}
\left(t r_{1}=t r_{4} \wedge \phi\right)\left[u / t r_{3}\right] \mid \\
t r_{2}=t r_{3} \cdot t r_{4} \text { and } u \text { does not syntactically appear in } t r_{3}
\end{array}\right\} \\
\text { SPLIT }_{\mathrm{EQ}-\mathrm{VAR}-2} & =\left\{\begin{array}{l}
t r_{1}=t r_{4} \wedge t r_{5} \cdot t r_{6} \in \epsilon \wedge \phi \mid \\
t r_{2}=t r_{3} \cdot t r_{4} \text { and } t r_{3}=t r_{5} \cdot u \cdot t r_{6}
\end{array}\right\}
\end{aligned}
$$

Variable $u$ is eliminated from the premises contained in the set $\operatorname{Split}_{\text {Eq-Var-1 }}$. The second set Split $_{\text {Eq-Var-2 }}$ captures cases where $u$ does syntactically appear in $t r_{3}$. Variable $u$ might still appear in some of the premises of Spliteq-Var-2.

The set Split ${ }_{\text {Eq-Var }}^{\prime}$ in Eq-VAR captures the second case, namely when $w_{u}$ does not coincide with a word denoted by a prefix of $t r_{2}$, written $t r_{3} \cdot v \cdot t r_{4}$ for some variable $v$. The premises in $\mathrm{SPLIT}_{\mathrm{EQ}-\mathrm{VAR}}^{\prime}$ are partitioned into two sets, namely SPlit ${ }_{\text {Eq-VAR-1 }}^{\prime}$ and Split ${ }_{\text {EQ-VAR-2 }}^{\prime}$ :

$$
\begin{aligned}
& \operatorname{SPLIT}_{\mathrm{EQ}-\mathrm{VAR}-1}^{\prime}=\left\{\begin{array}{l}
\left(\left(t r_{1}=v_{2} \cdot t r_{4} \wedge \phi\right)\left[u / t r_{3} \cdot v_{1}\right]\right)\left[v / v_{1} \cdot v_{2}\right] \mid \\
t r_{2}=t r_{3} \cdot v \cdot t r_{4} \text { and } u \text { appears neither in } t r_{3} \text { nor in } v
\end{array}\right\} \\
& \mathrm{SPLIT}_{\mathrm{EQ}-\mathrm{VAR}-2}^{\prime}
\end{aligned}=\left\{\begin{array}{l}
\left(t r_{1}=u_{2} \cdot t r_{4} \wedge u_{1} \cdot u_{2}=t r_{3} \cdot u_{1} \wedge \phi\right)\left[u / t r_{3} \cdot u_{1}\right] \\
t r_{2}=t r_{3} \cdot u \cdot t r_{4} \text { and } u \text { does not appear in } t r_{3}
\end{array}\right\}, ~ \$
$$

The premises in $\operatorname{Split}_{\text {Eq-Var-1 }}^{\prime}$ mention neither $u$ nor $v$. The set $\operatorname{Split}_{\text {Eq-VAR-2 }}^{\prime}$ captures cases where $u$ in the left-hand side overlaps with its occurrence on the right-hand side. Cases where $u$ appears in $t r_{3}$ are captured in SPLITEQ-Var .

Rule EQ-Word eliminates the word $w$ from the equality $w \cdot t r_{1}=t r_{2} \wedge \phi$ :

$$
\text { EQ-Word }: \frac{\operatorname{SPLIT}_{\mathrm{EQ}-\mathrm{Word}} \cup \mathrm{SPLIT}_{\mathrm{EQ}-\mathrm{Word}}^{\prime}}{w \cdot t r_{1}=t r_{2} \wedge \phi}
$$

Again, we define two sets representing the premises of the rule:

$$
\begin{aligned}
& \mathrm{SPLIT}_{E Q-W O R D}=\left\{t r_{3} \in w \wedge t r_{4}=t r_{1} \wedge \phi \mid t r_{2}=t r_{3} \cdot t r_{4}\right\} \\
& \mathrm{SPLIT}_{\mathrm{EQ}-\mathrm{WORD}}^{\prime}=\left\{\left(t r_{3} \cdot v_{1} \in w \wedge v_{2} \cdot t r_{4}=t r_{1} \wedge \phi\right)\left[v / v_{1} \cdot v_{2}\right] \mid t r_{2}=t r_{3} \cdot v \cdot t r_{4}\right\}
\end{aligned}
$$

To simplify the presentation, we do not present suffix versions for rules Eq-VAR and EQ-Word. Such rules match suffixes instead of prefixes and simply mirror the rules described above.

### 4.3 Removing Membership Predicates

We use rules Reg-Neg, Memb, Not-Memb, Reg-Split and Reg-Len to simplify and eliminate membership predicates. We describe them below.

Rule REG-NEG replaces the negation of a membership predicate in a regular expression $\mathcal{R}$ with a membership predicate in its complement $\mathcal{R}^{C}$.

$$
\text { REG-NEG }: \frac{t r \in \mathcal{R}^{C} \wedge \phi}{\neg(t r \in \mathcal{R}) \wedge \phi}
$$

Rule Memb eliminates the predicate $w \in \mathcal{R}$ in case the word $w$ belongs to the language $\mathcal{L}(\mathcal{R})$ of the regular expression $\mathcal{R}$. If $w$ does not belong to $\mathcal{L}(\mathcal{R})$ then rule Not-Memb closes this branch of the proof.

$$
\text { Memb : } \frac{\phi}{w \in \mathcal{R} \wedge \phi} w \in \mathcal{L}(\mathcal{R}) \quad \text { Not-Memb }: \frac{*}{w \in \mathcal{R} \wedge \phi} w \notin \mathcal{L}(\mathcal{R})
$$

Rule Reg-Split simplifies membership predicates of the form $t r \cdot t r^{\prime} \in \mathcal{R}$. Given such a predicate, the rule replaces it with a disjunction $\bigvee_{i=1}^{n}(t r \in$ $\left.\mathcal{R}_{i} \wedge t r^{\prime} \in \mathcal{R}_{i}^{\prime}\right)$ where the set $\left\{\left(\mathcal{R}_{i}, \mathcal{R}_{i}^{\prime}\right)\right\}_{i=1}^{n}$ is finite and only depends on the regular expression $\mathcal{R}$. To define this set, represent $\mathcal{L}(\mathcal{R})$ using some arbitrary but fixed finite automaton $\left(S, s_{0}, \delta, F\right)$. Assume $S=\left\{s_{0}, \ldots, s_{n}\right\}$. Choose the regular expressions $\mathcal{R}_{i}, \mathcal{R}_{i}^{\prime}$ such that: (1) $\mathcal{R}_{i}$ has the same language as the automaton $\left(S, s_{0}, \delta,\left\{s_{i}\right\}\right)$, and (2) $\mathcal{R}_{i}^{\prime}$ has the same language as the automaton $\left(S, s_{i}, \delta, F\right)$. For any word $w_{t r} \cdot w_{t r^{\prime}}$ denoted by $t r \cdot t r^{\prime}$ and accepted by $\mathcal{R}$, there will be a state $s_{i}$ in $S$ such that $w_{t r}$ is accepted by $\mathcal{R}_{i}$ and $w_{t r^{\prime}}$ is accepted by $\mathcal{R}_{i}^{\prime}$. Given a regular expression $\mathcal{R}$, we let $\mathcal{F}(\mathcal{R})$ denote the set $\left\{\left(\mathcal{R}_{i}, \mathcal{R}_{i}^{\prime}\right)\right\}_{i=1}^{n}$ above.

$$
\text { Reg-Split }: \frac{\left\{t r \in \mathcal{R}^{\prime} \wedge t r^{\prime} \in \mathcal{R}^{\prime \prime} \wedge \phi \mid\left(\mathcal{R}^{\prime}, \mathcal{R}^{\prime \prime}\right) \in \mathcal{F}(\mathcal{R})\right\}}{t r \cdot t r^{\prime} \in \mathcal{R} \wedge \phi}
$$

Rule Reg-Len can only be applied in certain cases. To identify these cases, we define the condition $\Gamma(\phi, u)$ which states, given a formula $\phi$ and a variable $u$, that $u$ is not used in any membership predicate or in any (dis)equation in $\phi$. In other words, the condition states that if $u$ occurs in $\phi$ then it occurs in a length predicate. The rule REG-Len replaces, in one step, all the membership predicates $\left\{u \in \mathcal{R}_{i}\right\}_{i=1}^{n}$ with an arithmetic constraint $\operatorname{Len}\left(\mathcal{R}_{1} \cap \ldots \cap \mathcal{R}_{m}, u\right)$. This arithmetic constraint expresses that the length $|u|$ of variable $u$ belongs to the semi-linear set corresponding to the Parikh image of the intersection of all regular expressions $\left\{\mathcal{R}_{i}\right\}_{i=1}^{n}$ appearing in membership predicates of variable $u$. It is possible to determine a representation of this semi linear set by starting from a finite state automaton representing the intersection $\cap_{i} \mathcal{R}_{i}$ and replacing all letters with a unique arbitrary letter. The obtained automaton is determinized and the semi linear set is deduced from the length of the obtained lasso if any (notice that since the automaton is deterministic and its alphabet is a singleton, its form will be either a lasso or a simple path.) After this step, there will be no membership predicates involving $u$.

$$
\text { REG-LEN }: \frac{\operatorname{Len}\left(\mathcal{R}_{1} \cap \ldots \cap \mathcal{R}_{m}, u\right) \wedge \phi}{u \in \mathcal{R}_{1} \wedge \ldots \wedge u \in \mathcal{R}_{m} \wedge \phi} \Gamma(\phi, u)
$$

### 4.4 Propagating Term Lengths

The rule Term-Leng is the only inference rule in the fourth group. It substitutes the expression $|t r|+\left|t r^{\prime}\right|$ for every occurrence in $\phi$ of the expression $\left|t r \cdot t r^{\prime}\right|$.

$$
\text { TERM-LENG }: \frac{\phi\left[\left|t r \cdot t r^{\prime}\right| /|t r|+\left|t r^{\prime}\right|\right]}{\phi}\left|t r \cdot t r^{\prime}\right| \text { appears in } \phi
$$

We can also add rules to systematically add the length predicate $|t r|=\left|t r^{\prime}\right|$ each time an equality $t r=t r^{\prime}$ appears in a formula; however, such rules are not necessary for the completeness of our procedure, as shown in the next section.

## 5 Completeness of the Procedure

In this section, we define a class of formulae of acyclic form (we say a formula is in acyclic form, or acyclic for short) for which the decision procedure in Section 4 is guaranteed to terminate. For simplicity, we assume w.l.o.g that the formula is a conjunction of predicates and negated predicates.

Non-termination may be caused by an infinite chain of applications of rule EQ-VAR of Section 4.2 for removing equalities. Consider for instance the equality $u \cdot v=v \cdot u$. One of the cases generated within the disjunct $\operatorname{SPLIT}_{\mathrm{EQ}-\mathrm{Var}-1}^{\prime}$ of EQ-VAR is $v_{1} \cdot v_{2}=v_{2} \cdot v_{1}$. This is the same as the original equality up to renaming of variables. In this case, the process of removing equalities clearly does not terminate. To prevent this, we will require that no variable can appear on both sides of an equality. We also need to prevent the repetition of a variable inside one side of an equality. This is needed in cases like $u \cdot u=v \cdot v$ where $\operatorname{SPLIT}_{\mathrm{EQ}-\mathrm{VAR}-1}^{\prime}$ includes $v_{1}=v_{2} \cdot v_{1} \cdot v_{2}$, with a variable $v_{1}$ on both sides of the equality, which is the situation which we wanted to prevent at the first place. These restrictions must hold initially and must be preserved by applications of any of the rules presented in Sections 4. Attention must be given to rules that modify equalities. Rules such as EQ-VAR involve substitution of a variable from one side of an equality by a term from the other side. We need to prevent chains of such substitutions that cause variables to appear several times in a (dis)equality. Acyclic formulae must also guarantee that the undesired cases cannot appear after a use of Diseq-Split of Section 4.1 that transforms a disequality to equalities. We respectively state preservation of these restriction and termination of the procedure of Section 4 in theorems 1 and 2 at the end of this Section. First, we need some definitions.
Linear formulae. A formula in $\mathcal{E}_{e, r, l}$ is said to be linear if it contains no (dis)equality where a variable appears more than once.
Given a conjunction $\phi$ in $\mathcal{E}_{e, r, l}$ involving $m$ (dis)equalities, we can build a dependency graph $G_{\phi}=(N, E$, label, map) in the following way. We order the (dis)equalities from $e_{1}$ to $e_{m}$, where each $e_{j}$ is of the form $\operatorname{lhs}(j) \approx \operatorname{rhs}(j)$ for $j: 1 \leq j \leq m$ and $\approx \in\{=, \neq\}$. For each $j: 1 \leq j \leq m$, a node $n_{2 j-1}$ is used to refer to the left-hand side of the $j^{\text {th }}$ (dis)equality, and $n_{2 j}$ to its right-hand side. For example, two different nodes are used even in the case of the simple equality $u=u$, one to refer to the left-hand side, and the other to refer the right-hand side. $N$ is then the set of $2 \times m$ nodes $\left\{n_{i} \mid i: 1 \leq i \leq 2 \times m\right\}$. The mapping label associates the term lhs ( $j$ ) (resp. rhs $(j)$ ) to each node $n_{2 j-1}$ (resp. $n_{2 j}$ ) for $j: 1 \leq j \leq m$. label is not necessarily a one to one mapping. The mapping map : $E \rightarrow\{$ rel, var $\}$ labels edges as follows: $\operatorname{map}\left(n, n^{\prime}\right)=$ rel for each $\left(n, n^{\prime}\right)=\left(n_{2 j-1}, n_{2 j}\right)$ for each $j: 1 \leq j \leq m$, and map $\left(n, n^{\prime}\right)=\operatorname{var}$ iff
$n \neq n^{\prime}$, and label $(n)$ and label $\left(n^{\prime}\right)$ have some common variables. By construction, map is defined to be total, i.e., $E$ contains only edges that are labeled by map.
A dependency cycle in $G_{\phi}=(N, E$, label, map $)$ is a cycle where successive edges have alternating labels. Formally, a dependency cycle is a sequence of distinct nodes $n_{0}, n_{1}, \ldots, n_{k}$ in $N$ with $k \geq 1$ such that 1) for every $i: 0 \leq i \leq k$, $\operatorname{map}\left(n_{i}, n_{i+1 \%(k+1)}\right)$ is defined, and 2) for each $i: 0 \leq i<k, \operatorname{map}\left(n_{i}, n_{i+1}\right) \neq$ $\operatorname{map}\left(n_{i+1}, n_{i+2 \%(k+1)}\right)$.
Acyclic graph. A conjunction $\phi$ in $\mathcal{E}_{e, r, l}$ is said to be acyclic iff it is linear and its dependency graph does not contain any dependency cycle.

Theorem 1. Application of rules of Section 4 preserves acyclicity.
An ordered procedure is any procedure that applies the rules of Section 4 on a formula in $\mathcal{E}_{e, r, l}$ in the four following phases. In the first phase, all disequalities are eliminated using Diseq-Split and Not-Eq. In the second phase, the procedure eliminates one equality at a time by repeatedly applying EQ-VAR, Eq-Word and Eq. In the third phase, membership predicates are eliminated by repeatedly applying Reg-Neg, Memb, Not-Memb, Reg-Split and Reg-Len. In the last phase, arithmetic predicates are solved using a standard decision procedure [3].

Theorem 2. Ordered procedures terminate on acyclic formulae.

## 6 Complete Verification of String-Processing Programs

The analysis of string-processing programs has gained importance due to the increased use of string-based APIs and protocols, for instance in the context of databases and Web programming. Much of the existing work has focused on the detection of bugs or the synthesis of attacks; in contrast, the work presented in this paper primarily targets verification of functional correctness. The following sections outline how we use our logic $\mathcal{E}_{e, r, l}$ for this purpose. On the one hand, our solver is designed to handle the satisfiability checks needed when constructing finite abstractions of programs, with the help of predicate abstraction [11, 13] or Impact-style algorithms [19]; since $\mathcal{E}_{e, r, l}$ can express both length properties and regular expressions, it covers predicates sufficient for a wide range of verification applications. On the other hand, we propose a constraint-based Craig interpolation algorithm for the automatic refinement of program abstractions (Section 6.2), leading to a completeness result in the style of [16]. We represent programs in the framework of Horn clauses [20, 12], which make it easy to handle language features like recursion; however, our work is in no way restricted to this setting.

### 6.1 Horn Constraints with Strings

In our context, a Horn clause is a formula $H \leftarrow C \wedge B_{1} \wedge \cdots \wedge B_{n}$ where $C$ is a formula (constraint) in $\mathcal{E}_{e, r, l}$; each $B_{i}$ is an application $p\left(t_{1}, \ldots, t_{k}\right)$ of a relation
symbol $p \in \mathcal{R}$ to first-order terms; $H$ is either an application $p\left(t_{1}, \ldots, t_{k}\right)$ of $p \in \mathcal{R}$ to first-order terms, or the constraint false. $H$ is called the head of the clause, $C \wedge B_{1} \wedge \cdots \wedge B_{n}$ the body. A set $\mathcal{H C}$ of Horn clauses is called solvable if there is an assignment that maps every $n$-ary relation symbol $p$ to a word formula $C_{p}\left[x_{1}, \ldots, x_{n}\right]$ with $n$ free variables, such that every clause in $\mathcal{H C}$ is valid. Since Horn clauses can capture properties such as initiation and consecution of invariants, programs can be encoded as sets of Horn clauses in such a way that the clauses are solvable if and only if the program is correct.

Example 1. The example from Section 2 is represented by the following set of Horn clauses, encoding constraints on the intermediate assertions Pre, $P_{1}, P_{2}, P_{3}$. Note that the clauses closely correspond to the verification conditions given in Fig. 2. Any solution of the Horn clauses represents a set of mutually inductive invariants, and witnesses correctness of the program.

$$
\begin{aligned}
\operatorname{Pre}(s) & \leftarrow \text { true } & & P_{3}(s) \leftarrow P_{2}(s) \\
P_{1}\left(s^{\prime}\right) & \leftarrow s^{\prime}=\epsilon \wedge \operatorname{Pre}(s) & & \text { false } \leftarrow s \in(a \mid b)^{*} \cdot b a \cdot(a \mid b)^{*} \wedge P_{3}(s) \\
P_{2}(s) & \leftarrow P_{1}(s) & & \text { false } \leftarrow \forall k .2 k \neq|s| \wedge P_{3}(s) \\
P_{2}(" a " \cdot s . " b ") & \leftarrow P_{2}(s) & & \text { (s) }
\end{aligned}
$$

Algorithms to construct solutions of Horn clauses with the help of predicate abstraction have been proposed for instance in [12]; in this context, automatic solving is split into two main steps: 1) the synthesis of predicates as building blocks for solutions, and 2) the construction of solutions as Boolean combinations of the predicates. The second step requires a solver to decide consistency of sets of predicates, as well as implication between predicates (a set of predicates implies some other predicate); our logic is designed for this purpose.
$\mathcal{E}_{e, r, l}$ covers a major part of the string operations commonly used in software programs; further operations can be encoded elegantly, including:

- extraction of substring $v$ of length len from a string $u$, starting at position pos, which is defined by the formula:

$$
u=p \cdot v \cdot s \wedge|v|=l e n \wedge|p|=p o s
$$

- replacement of the substring $v$ (of length len, starting at position pos) by $v^{\prime}$, resulting in the new overall string $u^{\prime}$ :

$$
u=p \cdot v \cdot s \wedge u^{\prime}=p \cdot v^{\prime} \cdot s \wedge|v|=l e n \wedge|p|=p o s
$$

- search for the first occurrence of a string, using either equations or regular expression constraints.


### 6.2 Constraint-Based Craig Interpolation

In order to synthesize new predicates for verification, we propose a constraintbased Craig interpolation algorithm [6]. We say that a formula $I[\bar{s}]$ is an interpolant of a conjunction $A[\bar{s}], B[\bar{s}]$ over common variables $\bar{s}=s_{1}, \ldots, s_{n}$ (and

```
Algorithm 1: Constraint-based interpolation of string formulae.
    Input: Interpolation problem \(A[\bar{s}] \wedge B[\bar{s}]\) with common variables \(\bar{s}\); bound \(L\).
    Output: Interpolant \(s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}\); or result Inseparable.
    \(A w \leftarrow \emptyset ; B w \leftarrow \emptyset ;\)
    while there is \(R E \mathcal{R}\) of size \(\leq L\) such that \(A w \subseteq \mathcal{L}(\mathcal{R})\) and \(B w \cap \mathcal{L}(\mathcal{R})=\emptyset\) do
        if \(A[\bar{s}] \wedge \neg\left(s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}\right)\) is satisfiable with assignment \(\eta\) then
            \(A w \leftarrow A w \cup\left\{\eta\left(s_{1}\right)|\cdots| \eta\left(s_{n}\right)\right\} ;\)
        else if \(B[\bar{s}] \wedge\left(s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}\right)\) is satisfiable with assignment \(\eta\) then
            \(B w \leftarrow B w \cup\left\{\eta\left(s_{1}\right)|\cdots| \eta\left(s_{n}\right)\right\} ;\)
        else
            return \(s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R} ;\)
        end
    end
    return Inseparable;
```

possibly including further local variables), if the conjunctions $A[\bar{s}] \wedge \neg I[\bar{s}]$ and $B[\bar{s}] \wedge I[\bar{s}]$ are unsatisfiable. In other words, an interpolant $I[\bar{s}]$ is an overapproximation of $A[\bar{s}]$ that is disjoint from $B[\bar{s}]$. It is well-known that interpolants are suitable candidates for predicates in software model checking; for a detailed account on the use of interpolants for solving Horn clauses, we refer the reader to [22].

Our interpolation procedure is shown in Alg. 1, and generates interpolants in the form of regular constraints separating $A[\bar{s}]$ and $B[\bar{s}]$. This means that interpolants are not arbitrary formulae in the logic $\mathcal{E}_{e, r, l}$, but are restricted to the form $s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}$, where "|" $\in \Sigma$ is a distinguished separating letter, and $\mathcal{R}$ is a regular expression. In addition, only interpolants up to a bound $L$ are considered; $L$ can limit, for instance, the length of the regular expression $\mathcal{R}$, or the number of states in a finite automaton representing $\mathcal{R}$.

Alg. 1 maintains finite sets $A w$ and $B w$ of words representing solutions of $A[\bar{s}]$ and $B[\bar{s}]$, respectively. In line 2 , a candidate interpolant of the form $s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}$ is constructed, in such a way that $\mathcal{L}(\mathcal{R})$ is a superset of $A w$ but disjoint from $B w$. The concrete construction of candidate interpolants of size $\leq L$ can be implemented in a number of ways, for instance via an encoding as a SAT or SMT problem (as done in our implementation), or with the help of learning algorithms like $L^{*}$ [1]. It is then checked whether $s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}$ satisfies the properties of an interpolant (lines 3,5), which can be done using the string solver developed in this paper. If any of the properties is violated, the constructed satisfying assignment $\eta$ gives rise to a further word to be included in $A w$ or $B w$.

Lemma 2 (Correctness). Suppose bound $L$ is chosen such that it is only satisfied by finitely many formulae $s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}$. Then Alg. 1 terminates and either returns a correct interpolant $s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}$, or reports Inseparable.

By iteratively increasing bound $L$, eventually a regular interpolant for any (unsatisfiable) conjunction $A[\bar{s}] \wedge B[\bar{s}]$ can be found, provided that such an inter-
polant exists at all. This scheme of bounded interpolation is suitable for integration in the complete model checking algorithm given in [16]: since only finitely many predicates can be inferred for every value $L$, divergence of model checking is impossible for any fixed $L$. By globally increasing $L$ in an iterative manner, eventually every predicate that can be expressed in the form $s_{1}\left|s_{2}\right| \cdots \mid s_{n} \in \mathcal{R}$ will be found.

## 7 Implementation

We have implemented our algorithm in a tool called NorN ${ }^{5}$ The tool takes as input a formula in the logic described in Section 3, and returns either Sat together with a witness of satisfiability (i.e., concrete string values for all variables), or Unsat. Norn first converts the given formula to DNF, after which each disjunct goes through the following steps:

1. Recursively split equalities, backtracking if necessary, until no equality constraints are left.
2. Recursively split membership constraints, again backtracking if necessary, and compute the language of each variable. From the language, we extract length constraints which we add to the formula.
3. Solve the remaining length constraints using Princess [3].

We will now explain the second step in more detail. Assume that we have a membership constraint $\operatorname{tr} \in A$, where $A$ is an automaton (Norn makes use of DK.BRICS.AUTOMATON [21] for all automata operations). We can remove a sequence of trailing constants $a_{1} a_{2} \cdots a_{k}$ in $t r=t r^{\prime} \cdot a_{1} a_{2} \cdots a_{n}$ by replacing the constraint with $\operatorname{tr}^{\prime} \in \operatorname{rev}\left(\delta_{a_{k} \cdots a_{2} a_{1}}(\operatorname{rev}(A))\right)$, where $\delta_{s}(A)$ denotes the derivative of $A$ w.r.t. the string $s$, and $\operatorname{rev}(A)$ denotes the reverse of $A$. We now have a membership constraint $s_{1} \cdots s_{n} \in A^{\prime}$ where the term consists of a number of segments $s_{i}$, each of the form $a_{1} \cdots a_{n_{i}} X_{i}$, i.e., a number of constants followed by a variable. The procedure keeps, at each step, a mapping $m$ that maps each variable to an automaton representing the language it admits. For the constraint to be satisfiable, the constraints $s_{1} \in A_{1}^{\prime}$ and $s_{2} \cdots s_{n} \in A_{2}^{\prime}$ must be satisfiable for some pair $\left(A_{1}, A_{2}\right)$ in the splitting of $A^{\prime}$. This means that we can update our mapping by $m\left(X_{i}\right)=m\left(X_{i}\right) \cap \delta_{a_{1} \cdots a_{n_{i}}}\left(A_{1}\right)$ and recurse on $s_{2} \cdots s_{n} \in A_{2}^{\prime}$. If at any point any automaton in the mapping becomes empty, the membership constraint is unsatisfiable, and we backtrack.

If, in the third step, Princess tells that the given formula is satisfiable, it gives concrete lengths for all variables. By restricting each variable to the solution given by Princess and reversing the substitutions performed in step 1, we can compute witnesses for the variables in the original formula.

Norn can be used both as a library and as a command line tool. In addition to the logic in Section 3, Norn supports character ranges (e.g. $[a-c]$ ) and the wildcard character (.) in regular expressions. It also supports the divisibility

[^0]| Program | Property | Time |
| :--- | :--- | :--- |
| $a^{n} b^{n}$ (Fig. 1) | $s \notin(a+b)^{*} \cdot b a \cdot(a+b)^{*} \wedge \exists k .2 k=\|s\|$ | 8.0 s |
| StringReplace | pre: $s \in(a+b+c)^{*} ;$ post: $s \in(a+c)^{*}$ | 4.5 s |
| ChunkSplit | pre: $s \in(a+b)^{*} ;$ post: $s \in(a+b+c)^{*}$ | 5.5 s |
| Levenshtein | dist $\leq\|s\|+\|t\|$ | 5.3 s |
| HammingDistance | dist $=\|v\|$ if $u \in 0^{*}, v \in 1^{*}$ | 27.1 s |

Table 1. Verification runtime for a set of string-processing programs. Experiments were done on an Intel Core i5 machine with 3.2 GHz , running 64 bit Linux.
predicate $x$ div $y$, which says that $x$ divides $y$. This translates to the arithmetic constraint $x=y * n$, where $n$ is a free variable.

Model Checking. We have integrated Norn into the predicate abstraction-based model checker Eldarica [14], on the basis of the algorithm and interpolation procedure from Section 6 . We use the regular interpolation procedure from Section 6.2 in combination with an ordinary interpolation procedure for Presburger arithmetic to infer predicates about word length. Table 1 gives an overview of preliminary results obtained when analyzing a set of hand-written stringprocessing programs. Although the programs are quite small, the presence of string operations makes them intricate to analyze using automated model checking techniques; most of the programs require invariants in form of regular expressions for verification to succeed. Our implementation is able to verify all programs fully automatically within a few seconds; since performance has not been the main focus of our implementation work so far, further optimization will likely result in much reduced runtimes. To the best of our knowledge, all of the programs are beyond the scope of other state-of-the-art software model checkers.

## 8 Conclusions and Future Work

In contrast to much of the existing work that has focused on the detection of bugs or the synthesis of attacks for string-manipulating programs; the work presented in this paper primarily targets verification of functional correctness. To achieve this goal, we have made several key contributions. First, we have presented a decision procedure for a rich logic of strings. Although the problem in its generality remains open, we are able to identify an expressive fragment for which our procedure is both sound and complete. We are not aware of any decision procedure with a similar expressive power. Second, we leverage on the fact that our logic is able to reason both about length properties and regular expressions in order to capture and manipulate predicates sufficient for a wide range of verification applications. Future works include experimenting with better integrations of the different theories, exploring different Craig interpolation techniques, and exploring the applicability of our framework to more general classes of string processing applications.

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## 9 Proof of Theorem 1

Proof. We only need to consider rules defined in Section 4.1 and Section 4.2 (since the other rules can not affect the acyclicity of the formula). Let $\phi$ be an acrylic formula of the form $\phi^{\prime} \wedge\left(\bigwedge_{i=1}^{m} e_{i}\right)$ where $\left(t r_{i} \approx_{i} t r_{i}^{\prime}\right)$ with $\approx_{i} \in\{=$ $, \neq\}$ for all $i \in\{1, \ldots, m\}$, and $\phi^{\prime}$ is a conjunction of length constraints and membership predicates. Let $G_{\phi}=\left(N_{\phi}, E_{\phi}\right.$, label $\left._{\phi}, \operatorname{map}_{\phi}\right)$ be the dependency graph associated to $\phi$ as defined 5 .

Depending on the applied proof rule, we have four cases to study:
Diseq-Split: We will show the claim for the case when the rule creates a formula defined by $\operatorname{Split}_{\text {Diseq-Split }}$. The other two cases are quite similar. Let us assume that the disequality $e_{m}: t r_{m} \neq t r_{m}^{\prime}$ is transformed into $t r_{m}=u \cdot c \cdot v \wedge t r_{m+1}=u \cdot c^{\prime} \cdot v^{\prime}$ where $u, v, v^{\prime}$ are fresh. Then, the resulting
formula $\phi_{\text {res }}$ is of the form $\phi^{\prime} \wedge \bigwedge_{i=1}^{m+1} e_{i}^{\prime}$ with $e_{i}=e_{i}^{\prime}$ for all $i \in\{1, \ldots, m-1\}$, $e_{m}^{\prime}=\left(t r_{m}=u \cdot c \cdot v\right)$ and $e_{m+1}^{\prime}=\left(t r_{m+1}=u \cdot c^{\prime} \cdot v^{\prime}\right)$. It is clear that $\phi_{\text {res }}$ is linear since $\phi$ is linear and $u, v, v^{\prime}$ are fresh variables.
Let $G_{\phi_{r e s}}=\left(N_{\phi_{\text {res }}}, E_{\phi_{\text {res }}}\right.$, label $\left._{\phi_{\text {res }}}, \operatorname{map}_{\phi_{\text {res }}}\right)$ be the corresponding dependency graph for $\phi_{\text {res }}$. We assume w.l.o.g that the set of nodes $N_{\phi_{\text {res }}}=$ $\left\{n_{i} \mid 1 \leq i \leq 2 m+2\right\}$ where the node $n_{2 i-1}$ is used to refer to the lefthand side of the $i$-th (dis)equality $e_{i}^{\prime}$ (or $e_{i}$ ) while the node $n_{2 i}$ is used to refer to the right-hand side of the $i$-th (dis)equality $e_{i}^{\prime}$ (or $e_{i}$ ) for all $i: 1 \leq i<m$. The node $n_{2 m-1}$ refers to left-hand side of the (dis)equality $e_{m}^{\prime}$ (or $e_{m}$ ) and $n_{2 m}$ left-hand side of the (dis)equality $e_{m+1}^{\prime}$ (or the righthand side of the (dis)-equality $e_{m}$ ). The nodes $n_{2 m+1}$ and $n_{2 m+2}$ refer to the right-hand side of the (dis)-equality $e_{m}^{\prime}$ and $e_{m+1}^{\prime}$. Then, it is easy to observe that label ${ }_{\phi}\left(n_{i}\right)=$ label $_{\phi_{r e s}}\left(n_{i}\right)$ for all $i: 1 \leq i \leq 2 m$. The set of edges of $G_{\phi_{\text {res }}}$ is defined as the union of $E_{\phi} \backslash\left\{\left(n_{2 m-1}, n_{2 m}\right)\right\}$ and $\left\{\left(n_{2 m-1}, n_{2 m+1}\right),\left(n_{2 m}, n_{2 m+2}\right),\left(n_{2 m+1}, n_{2 m+2}\right)\right\}$. Furthermore, we have $\operatorname{map}_{\phi_{\text {res }}}\left(n, n^{\prime}\right)=\operatorname{map}_{\phi}\left(n, n^{\prime}\right)$ if $\left(n, n^{\prime}\right) \in E_{\phi}, \operatorname{map}_{\phi_{\text {res }}}\left(n_{2 m-1}, n_{2 m+1}\right)=\mathrm{rel}$, $\operatorname{map}_{\phi_{\text {res }}}\left(n_{2 m}, n_{2 m+2}\right)=$ rel, and $\operatorname{map}_{\phi_{\text {res }}}\left(n_{2 m+1}, n_{2 m+2}\right)=$ var.
Observe that the difference between the dependency graph of the original formula and the graph of the formula after the application of the rule is the following. We remove the rel -edge between $n_{2 m-1}$ and $n_{2 m}$ and we add three edges as follows: an rel-edge between $n_{2 m-1}$ and $n_{2 m+1}$, a var-edge between $n_{2 m+1}$ and $n_{2 m+2}$, and finally an rel-edge between $n_{2 m}$ and $n_{2 m+2}$. The proof is done by contradiction. Let us assume that $G_{\phi_{r e s}}$ has a dependency cycle: There is sequence of distinct nodes $q_{0}, q_{1}, \ldots, q_{k}$ in $N_{\phi_{\text {res }}}$ with $k \geq 1$ such that 1 ) for every $i: 0 \leq i \leq k, \operatorname{map}\left(q_{i}, q_{i+1 \%(k+1)}\right)$ is defined, and
2) for each $i: 0 \leq i<k, \operatorname{map}\left(q_{i}, q_{i+1}\right) \neq \operatorname{map}\left(q_{i+1}, q_{i+2 \%(k+1)}\right)$.

Observe that there is an index $j: 0 \leq j \leq k$ such that $q_{j} \in\left\{n_{2 m+1}, n_{2 m+2}\right\}$, otherwise it is already a dependency cycle in $G_{\phi}$ (which is a contradiction). We assume that $j$ is the smallest of such index. This implies that there is an index $\ell: j<\ell \leq k$ such that $q_{\ell} \in\left\{n_{2 m+1}, n_{2 m+2}\right\} \backslash\left\{q_{j}\right\}$ (since the node $q_{j}$ is connected only by two edges and one of them is shared with $q_{\ell}$ ). Moreover, it is easy to see that $k>3$ since the nodes $n_{2 m-1}$ and $n_{2 m}$ should appear in the dependency cycles of $G_{\phi}$.
There are only three cases to consider depending on the position of $j$ and $\ell$ :

- If $1 \leq j<k-1$ then we have $\ell=j+1$ with $\ell<k$. This implies that the sequence of distinct nodes $q_{0}, q_{1}, \ldots, q_{j-1}, q_{j+2}, \ldots, q_{k}$ is a dependency cycle since the path $\left(q_{j-1}, q_{j}\right)\left(q_{j}, q_{j+1}\right)\left(q_{j+1}, q_{j+1}\right)$ in $G_{\phi_{\text {res }}}$ (with $\left.\operatorname{map}\left(q_{j-1}, q_{j}\right)=\operatorname{rel}, \operatorname{map}\left(q_{j}, q_{j+1}\right)=\operatorname{var} \operatorname{and} \operatorname{map}\left(q_{j+1}, q_{j+2}\right)=\mathrm{rel}\right)$ was replaced by the edge $\left(q_{j-1}, q_{j+2}\right)$ with $\operatorname{map}\left(q_{j-1}, q_{j+2}\right)=$ rel and so we respect the label alternation of the edges (which is a contradiction).
- If $j=k-1$ then we have $\ell=k$. This implies that the sequence of distinct nodes $q_{0}, q_{1}, \ldots, q_{k-2}$ is a dependency cycle since the path $\left(q_{k-2}, q_{k-1}\right)\left(q_{k-1}, q_{k}\right)\left(q_{k}, q_{0}\right)$ in $G_{\phi_{r e s}}\left(\right.$ with $\operatorname{map}\left(q_{k-2}, q_{k-1}\right)=$ rel, $\operatorname{map}\left(q_{k-1}, q_{k}\right)=\operatorname{var} \operatorname{and} \operatorname{map}\left(q_{k}, q_{0}\right)=$ rel) was replaced by the edge $\left(q_{k-2}, q_{0}\right)$ with $\operatorname{map}\left(q_{k-2}, q_{0}\right)=$ rel and so we respect the label alternation of the edges (which is a contradiction).
- If $j=0$ and $\ell=1$, then the sequence of distinct nodes $q_{2}, q_{3}, \ldots, q_{k}$ is a dependency cycle since the path $\left(q_{k}, q_{0}\right)\left(q_{0}, q_{1}\right)\left(q_{1}, q_{2}\right)$ in $G_{\phi_{r e s}}$ (with $\operatorname{map}\left(q_{k}, q_{0}\right)=\operatorname{rel}, \operatorname{map}\left(q_{0}, q_{1}\right)=\operatorname{var}$ and $\left.\operatorname{map}\left(q_{1}, q_{2}\right)=\operatorname{rel}\right)$ was replaced by the edge $\left(q_{k}, q_{2}\right)$ with $\operatorname{map}\left(q_{k}, q_{2}\right)=$ rel and so we respect the label alternation of the edges (which is a contradiction).
- If $j=0$ and $\ell=k$, then the sequence of distinct nodes $q_{1}, q_{2}, \ldots, q_{k-1}$ is a dependency cycle since the path $\left(q_{k-1}, q_{k}\right)\left(q_{k}, q_{0}\right)\left(q_{0}, q_{1}\right)$ in $G_{\phi_{\text {res }}}$ (with $\left.\operatorname{map}\left(q_{k-1}, q_{k}\right)=\operatorname{rel}, \operatorname{map}\left(q_{k}, q_{0}\right)=\operatorname{var} \operatorname{and} \operatorname{map}\left(q_{0}, q_{1}\right)=\operatorname{rel}\right)$ was replaced by the edge $\left(q_{k-1}, q_{1}\right)$ with $\operatorname{map}\left(q_{k-1}, q_{1}\right)=\mathrm{rel}$ and so we respect the label alternation of the edges (which is a contradiction).
Spliteq-Var $^{\text {, Eq-Word: We will show the claim for the } \text { Split }_{\text {Eq-Var }} \text {. The proof }}$ for the EQ-WORD is simpler since it does not introduce new nodes or edges in the dependency (modulo renaming).
Let first concentrate on the case Split $_{\text {Eq-VAR-1 }}$ (the other case $\operatorname{Split}_{\text {Eq-VAR-2 }}$ can't be applied due to the acyclic formula since the variable $u$ can't appear on both sides).
Let us assume that the equality $e_{m}=\left(t r_{m}=t r_{m}^{\prime}\right)$, with $t r_{m}=u \cdot t r$ and $t r_{m}^{\prime}=t r^{\prime} \cdot t r^{\prime \prime}$, is transformed into $t r=t r^{\prime \prime}$. Then, the resulting formula $\phi_{r e s}$ is of the form $\phi^{\prime}\left[u / t r^{\prime}\right] \wedge\left(\bigwedge_{i=1}^{m} e_{i}^{\prime}\right)$ with $e_{i}^{\prime}=e_{i}\left[u / t r^{\prime}\right]$ for all $i \in\{1, \ldots, m-1\}$ and $e_{m}^{\prime}=\left(t r=t r^{\prime \prime}\right)$.
The application of a such rule may be seen as two consecutive steps which preserve acyclic form:

1. removal of $u$ and $t r^{\prime}$ from the equality $e_{m}=\left(t r_{m}=t r_{m}^{\prime}\right)$. We obtain the formula $\phi_{1}$ which is of the form $\phi^{\prime} \wedge\left(\bigwedge_{i=1}^{m-1} e_{i}\right) \wedge\left(e_{m}^{\prime}\right)$
2. substitution of $u$ by $t r^{\prime}$ in $\phi_{1}$ and which leads to the formula $\phi_{\text {res }}$.

It is clear that $\phi_{1}$ is linear and that the dependency graph $G_{\phi_{1}}=$ $\left(N_{\phi_{1}}, E_{\phi_{1}}\right.$, label $\left._{\phi_{1}}, \operatorname{map}_{\phi_{1}}\right)$ associated to $\phi_{1}$ is free from dependency cycles since it consists of the graph $G_{\phi}$ where we have removed some varedges. Hence $\phi_{1}$ is an acyclic formula. We assume w.l.o.g that $N_{\phi_{1}}=N_{\phi}$, $\operatorname{label}_{\phi_{1}}\left(n_{j}\right)=\operatorname{label}_{\phi}\left(n_{j}\right)$ for all $j \in\{1, \ldots, 2 m-2\}$ and $n_{2 m-1}$ (resp. $n_{2 m}$ ) refers to the left-hand (right-hand) side of the equality $e_{m}^{\prime}$.
Now after the application of step 1 , we replace any occurrence of $u$ by the term $t r^{\prime}$. Let us assume that $\phi_{\text {res }}$ is not consistent. This means that there is a (dis)equality $e_{i}: \operatorname{tr}_{i}\left[u / t r^{\prime}\right] \approx_{i} \operatorname{tr}_{i}^{\prime}\left[u / t r^{\prime}\right]$ where a variable $v$ appears at least twice. This means that $v$ appears in $t r^{\prime}$ and appears in $t r_{i} \cdot t r_{i}^{\prime}$. There are two cases: (1) $u$ and $v$ appears in $t r_{i}$ (resp. $t r_{i}^{\prime}$ ), then we can construct a dependency cycle in $G_{\phi}$ as follows $n_{2 i-1} n_{2 m-1} n_{2 m}$ (reps. $n_{2 i} n_{2 m} n_{2 m-1}$ ), which contradicts the acyclicity assumption of $\phi$, or (2) $u$ appears in $t r_{i}$ and $v$ in $t r_{i}^{\prime}$ (resp. $v$ in $t r_{i}$ and $u$ in $t r_{i}^{\prime}$ ), then we can construct the following dependency graph $n_{2 i-1} n_{2 m-1} n_{2 m} n_{2 i}$ (resp. $n_{2 i} n_{2 m-1} n_{2 m} n_{2 i-1}$ ), which contradicts also the acyclicity assumption of $\phi$. Hence $\phi_{\text {res }}$ is linear.
Let us show now that the dependency graph of $\phi_{\text {res }}$ does not contain any dependent cycle.
Let $G_{\phi_{r e s}}=\left(N_{\phi}, E_{\phi_{r e s}}\right.$, label $\left._{\phi_{r e s}}, \operatorname{map}_{\phi_{\text {res }}}\right)$ be the corresponding dependency graphs for $\phi_{\text {res }}$. The difference between the dependency graph of the
formula $\phi_{1}$ and the graph of the formula $\phi_{\text {res }}$ after the second step is that we add some var -edges to the graph $G_{\phi_{1}}$.
The proof is done by contradiction. et us assume that $G_{\phi_{r e s}}$ has a dependency cycle: There is sequence of distinct nodes $q_{0}, q_{1}, \ldots, q_{k}$ in $N_{\phi_{\text {res }}}$ with $k \geq 1$ such that 1) for every $i: 0 \leq i \leq k$, map $\left(q_{i}, q_{i+1 \%(k+1)}\right)$ is defined, and 2) for each $i: 0 \leq i<k, \operatorname{map}\left(q_{i}, q_{i+1}\right) \neq \operatorname{map}\left(q_{i+1}, q_{i+2 \%(k+1)}\right)$.
Observe that there is $j: 0 \leq j<k$ such that $\operatorname{map}_{\phi_{\text {res }}}\left(q_{j}, q_{j+1}\right)=$ var is a newly added edge in $G_{\phi}$ with respect to $G_{\phi_{1}}$, otherwise it is already a dependency cycle in $G_{\phi_{1}}$ (which is a contradiction).
Now we can through the dependency cycle $q_{0}, q_{1}, \ldots, q_{k}$ and replace any newly added edge $\left(q_{j}, q_{j+1}\right)$ with $\operatorname{map}_{\phi_{\text {res }}}\left(q_{j}, q_{j+1}\right)=$ var by the sequence of nodes: (1) $q_{j} q_{2 m-1} q_{2 m} q_{j+1}$ with $\operatorname{map}_{\phi}\left(q_{j}, q_{2 m-1}\right)=\operatorname{var}, \operatorname{map}_{\phi}\left(q_{2 m-1}, q_{2 m}\right)=$ rel and $\operatorname{map}_{\phi}\left(q_{2 m}, q_{j+1}\right)=$ var, or $(2) q_{j} q_{2 m} q_{2 m-1} q_{j+1}$ with $\operatorname{map}_{\phi}\left(q_{j}, q_{2 m}\right)=$ $\operatorname{var}, \operatorname{map}_{\phi}\left(q_{2 m}, q_{2 m-1}\right)=$ rel and $\operatorname{map}_{\phi}\left(q_{2 m-1}, q_{j+1}\right)=\operatorname{var}$. Thus, we can remove all the newly edges and replace them by some edges in $G_{\phi}$. Hence we can obtain a sequence of nodes $p_{0}, p_{1} \ldots, p_{r}$ of $G_{\phi}$ such that such that 1) for every $i$ : $0 \leq i \leq r, \operatorname{map}\left(p_{i}, p_{i+1 \%(r+1)}\right)$ is defined, and 2) for each $i: 0 \leq i<r, \operatorname{map}\left(p_{i}, p_{i+1}\right) \neq \operatorname{map}\left(p_{i+1}, p_{i+2 \%(r+1)}\right)$.
Now, we have two cases:

- We have $p_{i} \neq p_{j}$ for all $i, j \in\{0, \ldots, r\}$ such that $i \neq j$ and hence $p_{0}, p_{1} \ldots, p_{r}$ is a dependency cycle in $G_{\phi}$ (which a contradiction).
- There are $i, j \in\{1, \ldots, r\}$ such that $i<j$ such that $p_{i}=p_{j}$ and for every $i^{\prime}, j^{\prime} \in\{i, \ldots, j-1\}$ such that $i^{\prime} \neq j^{\prime}$, we have $p_{j^{\prime}} \neq p_{i^{\prime}}$. Now we can show that $p_{i} p_{i+1} \ldots, p_{j-1}$ is a dependency graph in $G_{\phi}$ which also contradict the acyclicity of $\phi$. Observe that $j>i+1$ otherwise it is a contradiction of the linearity of $\phi$.
Split' $^{\text {Eq-Var }}$ : We will show the claim for the Split' ${ }_{\text {Eq-Var }}$.
Let first concentrate on the case Split' ${ }^{\text {Eq-VAr-1 }}$ (the other case Split' ${ }^{\text {Eq-VAR-2 }}$ can't be applied due to the acyclic formula since the variable $u$ can't appear on both sides).
Let us assume that the equality $e_{m}: t r_{m} \neq t r_{m}^{\prime}$, with $t r_{m}=u \cdot t r$ and $t r_{m}^{\prime}=t r^{\prime} \cdot v \cdot t r^{\prime \prime}$, is transformed into $t r=v_{2} \cdot t r^{\prime \prime}$. Then, the resulting formula $\phi_{\text {res }}$ is of the form $\phi^{\prime}\left[u / t r^{\prime} \cdot v_{1}\right]\left[v / v_{1} \cdot v_{2}\right] \wedge\left(\bigwedge_{i=1}^{m-1}\left(t r_{i}\left[u / t r^{\prime} \cdot v_{1}\right]\left[v / v_{1} \cdot v_{2}\right] \approx_{i}\right.\right.$ $\left.\left.t r_{i}^{\prime}\left[u / t r^{\prime} \cdot v_{1}\right]\left[v / v_{1} \cdot v_{2}\right]\right)\right) \wedge\left(t r=v_{2} \cdot t r^{\prime \prime}\right)$.
The application of a such rule may be seen as two consecutive steps which all preserve acyclic form:

1. removal of $v$ and its replacement by $v_{1} v_{2}$ in $\phi$. We obtain the formula $\phi_{1}$ which is of the form $\phi^{\prime}\left[v / v_{1} v_{2}\right] \wedge\left(\bigwedge_{i=1}^{m}\left(e_{i}\left[v / v_{1} v_{2}\right]\right)\right)$.
2. Then, we apply the $\operatorname{SpLIT}_{\mathrm{Eq}-\mathrm{VAR}-1}$ to $\phi_{1}$ to obtain $\phi_{\text {res }}$.

It is clear that $\phi_{1}$ is an acyclic formula and hence $\phi_{\text {res }}$ from the previous item.

## 10 Proof of Theorem 2

We need only to show that repeatedly applying Eq-Var, Eq-Word and Eq to the same equality will terminate. From Theorem 1, we know that after each
application of such rules, the acyclicity of the formula is persevered and hence its linearity. This implies that after application of such rules the size of the equality (i.e., the number of variables and constants) will be strictly smaller.


[^0]:    $\overline{{ }^{5} \text { Available at http://user.it.uu.se/~jarst116/norn/. }}$

